

MC-EMVS: Multi-Event-Camera Depth Estimation and Outlier Rejection by Refocused Events Fusion



Paper

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 Ground-truth (GT) Depth
 Confidence map (ours)

 ENVO [Zhou et al, 7RO 2021]
 Ours (H fusion)

 Smudged edges
 Sharp 3D edges







Journal reference: Ghosh and Gallego, "Multi-Event-Camera Depth Estimation and Outlier Rejection by Refocused Events Fusion", Advanced Intelligent Systems 2022.